

MICROCONTROLLER BASED DIGITAL CODE LOCK

PROJECT REPORT

SUBMITTED BY

**KABIL DAS K
KRISHNA PRIYA VINOD M
KURIAN MATHEW**

in partial fulfilment for the award of the degree

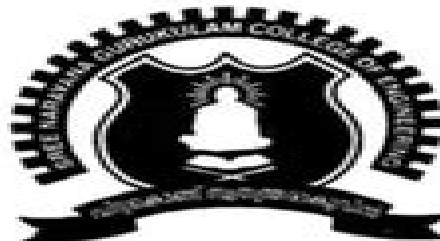
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BACHELOR OF TECHNOLOGY

In

ELECTRONICS AND COMMUNICATION

**SREE NARAYANA GURUKULAM COLLEGE OF ENGINEERING,
KADAYIRUPPU**



MG UNIVERSITY: KOTTAYAM

APRIL 2011

Microcontroller Based Digital Code Lock Project Report

S Ben Porath



Microcontroller Based Digital Code Lock Project Report:

Annual Report University of Ghana,2008 **Proceedings of the National Conference on Computing for Nation Development** ,2007 *Documentation Abstracts* ,1996 *Government Reports Announcements & Index* ,1992

Applied Science & Technology Index ,2000 **Arduino Based Digital Lasso Lock Security System Using Keypad** Daniel Bhaskaran Raju,2022 This thesis describes the development of the Arduino based lasso lock security system. It focuses on the security aspects of digital security systems by outlining the common issues. For this project a microcontroller was chosen and a test environment was created to experiment with and detect security flaws. The majority of people nowadays are concerned about how to protect their vital and personal things such as valuables and documents. As a result the majority of individuals use alarms to secure their lockers at home in order to ensure the safety of their valuables. However they may still be used through manual lock system procedures without providing any notice to the user when they are broken. This research project develops an enhanced alert system that uses a tension sensor and a numeric keypad to authenticate the user's identity in order to open the lasso locked box. This project describes a safe and simple security system that utilizes a load cell sensor to handle the locking process. The Arduino 4x4 keypad load cell potentiometer buzzer and Liquid Crystal Display LCD screen are used to hardwire the system. The ARDUINO IDE program was utilized to create the system's controlling statements in the Arduino controller. System testing ensures that a high degree of security is maintained resulting in optimum performance. Steps in the Development of Stand-alone Microcontroller Based Digital Systems Anuj Dua,1994

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problem most planets orbit the sun in elliptical orbits do these planets exhibit rotational motion rotational motion has two requirements all particles must move about a fixed axis and move in a circular path since the path of most planets is not circular they do not exhibit rotational motion problem

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rotational kinematics just like linear kinematics is descriptive and does not represent laws of nature with kinematics we can describe many things to great precision but kinematics does not consider causes for example a large angular acceleration describes a very rapid change in angular velocity without any consideration of its cause

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we have 8 ready to use problem sets on the topic of rotational kinematics these problem sets focus on the analysis of

situations involving a rigid object rotating in either a clockwise or counterclockwise direction about a given point the object's rotation speed may be increasing decreasing or remaining constant

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problem a merry go round has an initial angular velocity of 10.2 rpm at the end of the ride the brakes are applied giving it a constant angular deceleration of 0.032 rad/s^2 as the ride slows to a stop

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rotational kinematics in the section on uniform circular motion we discussed motion in a circle at constant speed and therefore constant angular velocity however there are times when angular velocity is not constant rotational motion can speed up

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evaluate problem solving strategies for rotational kinematics just by using our intuition we can begin to see how rotational quantities like θ , ω and α are related to one another for example if a motorcycle wheel has a large angular acceleration for a fairly long time it ends up spinning rapidly and rotates through many revolutions

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may 21 2023 directions of rotational kinematics vectors rigid body rotation whenever we talk about rotation there is something that is generally implied we are not talking about a point mass or a collection of independently moving point masses

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these are only true if the angular acceleration is constant but if it is constant these are a convenient way to relate all these rotational motion variables and you can solve a ton of problems using these rotational kinematic formulas

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problem a fan initially rotates clockwise at 9.0 rad/s but has a counterclockwise angular acceleration of 3.0 rad/s^2 and reaches a counterclockwise angular speed of 27 rad/s how much time did this change in the angular velocity take